

# JUAN SALAZAR

2000 Bay Area Blvd | Houston, TX 77058

786-975-9789 | juansal1204@gmail.com | <https://juansala.github.io/>

<b>Education</b>	<b>Massachusetts Institute of Technology (MIT), Cambridge, MA</b> M. Eng in Electrical Engineering and Computer Science   GPA: 4.4 <i>May 2022</i> B.S. in Aerospace Eng. (Conc. in Autonomous Systems) & Electrical Eng.   GPA: 4.4 <i>June 2020</i> Underactuated Robotics · Manipulation · Control · Space Systems Engineering
<b>Research &amp; Work Experience</b>	<b>ARES Corporation (NASA Johnson Space Center), Houston, TX</b> <i>January 2023 - Present</i> <i>Systems Engineer/ISS Robotics Analyst</i> <ul style="list-style-type: none"><li>• Design ISS robotic arm trajectories to assess kinematic feasibility of planned operations</li><li>• Present results at engineering review and ISS program management boards</li><li>• Develop applications to automate workflow and extend analysis software functionality in Python</li></ul> <b>Distributed Robotics Laboratory (CSAIL), Cambridge, MA</b> <i>July 2018 - May 2022</i> <i>Undergraduate/Graduate Research Assistant</i> <ul style="list-style-type: none"><li>• Developed autonomous coordination for soft robotic fish that led to publication</li><li>• Contributed to development of visual tracking algorithm using OpenCV and ROS</li><li>• Developed tools for computational design and control of underwater vehicles using Python</li></ul>
<b>Leadership</b>	<b>NASA BIG Idea Challenge (Extreme Terrain Mobility)</b> <i>November 2021 - June 2022</i> <i>Software &amp; Autonomy Lead</i> <ul style="list-style-type: none"><li>• Led a team of 5 to develop simulation for finalist lunar robot in 2022 BIG Idea Challenge</li><li>• Developed physics-based hexapod walking simulator using ROS, Python, and Gazebo to support real design trade studies</li><li>• Formulated software architecture and walking capability system requirements</li></ul> <b>MIT Rocket Team</b> <i>August 2018 - July 2019</i> <i>Payload Team Lead, Outreach Chair</i> <ul style="list-style-type: none"><li>• Led development of sensor payload for sounding rocket launched to ~10,000 ft</li><li>• Developed microcontroller firmware for onboard sensor operations and data storage in C</li></ul>
<b>Publications</b>	<b>Juan Salazar, Levi Cai, Braden Cook, Daniela Rus.</b> “Multi-Robot Visual Control of Autonomous Soft Robotic Fish.” Published, IEEE OES AUV Symposium, 2022.
<b>Skills &amp; Awards</b>	<b>Software:</b> Python, C/C++, Git, Gazebo, ROS, Linux, MATLAB <b>Hardware:</b> 3D Printers, Microcontrollers, Circuits & Electronics <b>Languages:</b> French (fluent), Spanish (fluent) <b>Awards:</b> 1st Place Team, 2018 Unified Engineering Flight Competition